(Distance from the robot center to the 3rd joint center)

Exhaust direction

R790 (Operable range of the 3rd joint center)

R505 (Min. rotation radius)

1290 (Distance from the robot center to the substrate center)

500x500 (Substrate size)

400 (Stroke)

768 (Lower level)

VAC.1 A-view

External connection panel details

Vacuum supply port Dia. 10 quick coupling

Vacuum break port Dia. 10 quick coupling

Removable panel for lithium battery replacement

Pressure sensor

Motor connector

Encoder connector

Signal connector

Substrate presence sensor

Substrate edge detection sensor

Wrist-block unit

Reference drawing

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JCR4400-400-AM

Substrate presence sensor

Substrate edge detection sensor

Pressure sensor

Motor connector

Encoder connector

Signal connector

Wrist-block unit

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